

Micromanipulator System NT-88=V3 Series

Fusion of Utmost Precision

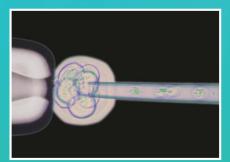
ICSI (Intracytoplasmic sperm injection) and IMSI (Intracytoplasmic morphologically selected sperm injection), IVF (In vitro fertilization) technologies that have received a lot of attention in recent years as a remedy for male infertility, require a highly precise manipulator to respond to delicate movement of the operator's hands.

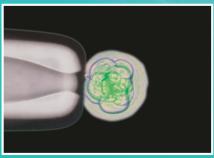
Stable, smooth manipulation is also required for injection to the stem cell, transgenics and electrophysiology.

The NT-88-V3 series, jointly developed by Nikon and Narishige, ensures easy operation and an unsurpassed level of precision. When used in combination with Nikon's high-performance microscopes, it provides strong support for cutting-edge biomedical research.

- Size is greatly reduced as the 3D motor-driven coarse control manipulator and 3D hydraulic fine micromanipulator are combined in a single unit.
- Assembly of the micromanipulator is fast and easy due to the extremely stable, one-piece mounting adapter.
- Wide varieties of microinjectors for holding or injecting specimens depending on use.



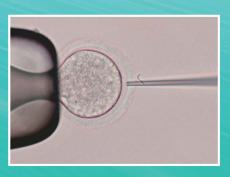


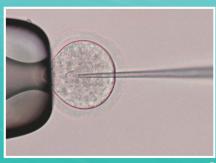


and Fine Mechanism









Oil-hydraulic Micromanipulators

3D Hydraulic Micromanipulator NT-88-V3

Combined 3D motor-driven coarse control manipulator and the 3D hydraulic fine micromanipulator realize remarkably compact and stable design.

- Less than half the size of a conventional model—minimal length tubes and cords—the manipulator fits easily into the incubator.
- Closer-to-the-center settings are possible, while reduced distance from manipulator mount to microelectrode tip increases stability.
- X-axis control knobs are located symmetrically on opposite sides of the joystick to eliminate left side/right side positioning problems.
- 10mm X-Y operating range provides versatility in manipulation at lower magnifications.
- A "resume" feature returns the pipette to the original position after the pipette has been raised for quicker, easier Petri dish changes.
- The universal joint is outfitted with an angle gauge, which ensures accurate-angle operation. The forward-mounted return mechanism facilitates Petri dish changing.
- Permits one-touch installation on an inverted microscope.





Hanging joystick design for optimal ergonomics and user comfort during long

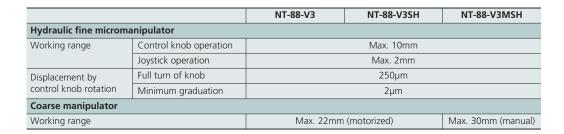
3D Hydraulic Micromanipulator (Single-hand type) NT-88-V3SH

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Suitable for experiments that do not require the holding side's pipette, such as the microinjection or microdissection to an adherent cell

3D Hydraulic Micromanipulator (Manual Single-hand type) NT-88-V3MSH

A manual 3D coarse positioning manipulator allows you to quickly move the micro-pipette to the ideal position. And the compact design allows you to position it closer to you with the control knob in easy reach.



Universal Joint UJ-V3

Universal Joint UJ-V3 allows the pipette holder to be moved in a single direction. The angle can be adjusted for both vertical and horizontal directions via two separate control knobs. The forward-mounted return mechanism facilitates changing the petri dish while the built-in angle gauge ensures accurate-angle operation. Moreover, because the UJ-V3 is mountable from above, unlike the conventional type, attachment and removal is much easier.



Pneumatic Microinjector IM-11-2*

The IM-11-2 allows suction and injection of a microsample with precision and operability comparable to oil hydraulic injectors. It is suitable for both injecting and holding during ICSI. Air bubbles do not enter the micropipette when the pneumatic microinjector is fitted.

Movement range: 40mm

* In the U.S.A., use IM-11-2A for clinical use.

Oil-type Microinjector IM-9B Pneumatic Injector IM-9C

The IM-9B, which is suitable for injection, and the IM-9C, which is suitable for holding, provide smoother and more stable maneuverability by applying a new mechanism to minimize backlashes. Also, their 53mm working distance, large-volume syringe and just-the-right-size control knob with graduated scales all contribute to easy control of the injection. The IM-9B has a glass syringe for easy confirmation of internal air bubbles while its new tube connector with a three-way stopcock makes for easier filling of oil without generating air bubbles.

	IM-9B	IM-9C		
Movement distance				
Movement range	53mm	53mm		
Full rotation of knob	500µm	6mm		
Control value				
Full rotation of knob	Approx. 10µl	Approx. 480µl		
Syringe	1,060µl glass type	4,240µl metal type		

Pipette Holder Clamper HIK-5



The HIK-5 is used to keep the pipette holder at the desired position, thereby simplifying pipette exchange. The magnetic clamper is attached to a bench or iron plate. Alternatively, it can be attached to the included round metal plate, which can be affixed at the desired location to a microscope stage using double-sided adhesive tape.



Microscope Adapters for NT-88-V3

Various adapters are available for use with Nikon microscopes. As both adapters and manipulators are compact, attaching them is very easy.



NS-TEV3 Mounting Adapter to use with inverted microscopes Ti and TE2000



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NS-T1 Mounting Adapter to use with inverted microscope TS100

Micromanipulators for electro-physiology applications

3D Water-Hydraulic Micromanipulator

The MHW-3 is a hydraulic micromanipulator for patch clamping that reduces unwanted drift due to temperature change. A cartridge with a one-to-five moving ratio enables fine control manipulation equivalent to an oil hydraulic manipulator. The drum type control unit enables high linear repeatability.

Movement range	Fine 2mm (X, Y and Z axes), coarse 30mm (X, Y and Z axes)
Full rotation of knob	50µm
Minimum graduation	Fine 0.2µm



MHW-3 with NN-L3 adapter, configured with patch amplifier

3D Motorized Micromanipulator

The MM-80 has been developed to satisfy the competing goals of "stability" and "compactness" that are essential for research work in electrophysiology.

The motorized micromanipulator is constructed in a simplified design with its controller employing simple-design push button switches. The drive unit embodies user-friendly convenient features which help reduce stress during experiments.

5		Fine 20mm (X, Y and Z axes), coarse 30mm (X, Y and Z axes)		
Driving speed	Minimum	Approx. 10µm/s*		
(Motorized fine drive)	Maximum	Approx. 150µm/s*		

* DC motor drive, theoretical value

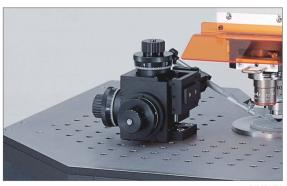
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Manual 3D Micromanipulators

The NMN-21 and -25 are designed for drift-free operation, making them ideal for delicate, patch-clamp research. The unit has no hydraulic system nor spring mechanism and its unique double-slider structure minimizes vibrations transmitted from the operator's hand to the tip of the pipette via the control knob. The unit's motor-less and actuator-less design also eliminates electromagnetic disturbances. The NMN-25 features a compact, space-saving design without a scale.

	NMN-21	NMN-25
Movement range	Fine 6mm (X, Y and Z axes), coarse 15mm (X, Y and Z axes)	Fine 6mm (X and Z axes), coarse 15mm (X and Z axes), combined coarse and fine working range 15mm (Y axis)
Full rotation of knob	Fine 250µm, coarse approx. 4mm	Fine 250µm (X and Z axes), approx. 250µm (Y axis)
Minimum graduation	Fine 1µm	—





NMN-21

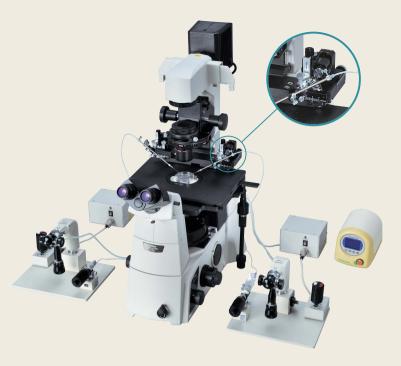


Recommended combination for various applications

For ICSI (Intracytoplasmic Sperm Injection), ES cell injection and nucleus transfer

The microinjection system is dedicated to floating cell applications. The inner diameter of the pipette tip is more than 5μ m. For the injection of the sperm, embryo-stem cell and nucleus, a manual injector is suitable as it accurately transmits the movement of user's hand via the handle.

Product	Unit	Model name	
Components			
Inverted microscope	1	Ti-U NAMC set	
3D hydraulic micromanipulator	1	NT-88-V3	
Microinjector (injection side)	1	IM-9B	
Oil-type microinjector (injection side)	1	IM-9C	
Thermal plate warmer: ThermoPlate TP series	1	TP-108R05	
Options for making pipettes			
Micropipette puller	1	PC-10	
Pipette grinder	1	EG-400	
Microforge	1	MF-900	
Glass capillaries	1	G-100	



For injection into adherent cells

The microinjection system for adherent cells incorporates a oneaxis oil hydraulic micromanipulator—it moves in the direction of a pipette—only on the injection side, since it does not require an injector on the holding side. A motorized injector that can accurately control the injection amount of DNA and fluorescence dyes is suitable.

Product	Unit	Model name	
Components			
Inverted microscope	1	Ti-U DIC set	
3D hydraulic micromanipulator (single-hand type)	1	NT-88-V3SH	
Mounting adapter	1	NS-TEV3	
1D hydraulic micromanipulator	1	MMO-220A	
Motorized microinjector	1	IM-300	
Thermal plate warmer: ThermoPlate TP series	1	TP-108R05	
Options for making pipettes			
Micropipette puller	1	PC-10	
Glass capillaries	1	GD-1	

Product	Unit	Model name		
Components				
Stereoscopic microscope	1	SMZ18 FL set		
Mechanical micromanipulator	1	MN-153		
Mounting adapter	1	NN-V, NR-2		
Motorized microinjector	1	IM-300		
Options for making pipettes				
Micropipette puller	1	PC-10		
Glass capillaries	1	GD-1		





Single-cell patch clamping with inverted microscope

This system is suitable for single-cell patch clamp experiments using an inverted microscope. Two units, one each for recording and stimulating, are included. A water-hydraulic micromanipulator effective for general manipulations is suitable.

Product	Unit	Model name
Components		
Inverted microscope	1	Ti-U DIC set
Mounting adapter	1	NN-L3
3D water-hydraulic micromanipulator	2	MHW-3
Patch amplifier adapter*	1	AP-12A/L/N or AP-13-2
Options for making pipettes		
Micropipette puller	1	PC-10
Microforge	1	MF-830
Glass capillaries	1	GD-1.2
Glass capillaries	1	GD-1.5

* Please select an adapter that suits the brand of patch amplifier used.



Single-cell patch clamping with upright microscope

This system is suitable for single-cell patch clamp experiments using an upright microscope. Two units, one each for recording and stimulating, are included. A water-hydraulic micromanipulator effective for general manipulations is suitable.

Product	Unit	Model name	
Components			
Upright microscope	1	FN1-FL-DIC set	
Mounting adapter	1	NN-R	
3D water-hydraulic micromanipulator	2	MHW-3	
Patch amplifier adapter*	1	AP-12A/L/N or AP-13-2	
Options for making pipettes			
Micropipette puller	1	PC-10	
Microforge	1	MF-830	
Glass capillaries	1	GD-1.2	
Glass capillaries	1	GD-1.5	

* Please select an adapter that suits the brand of patch amplifier used.



Manual patch clamping

This system is suitable for patch clamp experiments on slice cells using an upright microscope. The two stages that incorporate new functions were developed especially for the FN1. One is independent from the microscope and the other, a manual XY stage, enables the microscope's observation field to be changed. Though three waterhydraulic micromanipulators are used in the picture, any number can be selected.

Product	Unit	Model name
Components		
Upright microscope	1	FN1-FL-DIC set
Stage	1	ITS-FN1
3D water-hydraulic micromanipulator	3	MHW-3
Patch amplifier adapter*	2**	AP-12A/L/N, AP-13-2
Options for making pipettes		1
Micropipette puller	1	PC-10
Microforge	1	MF-830
Glass capillaries	1	GD-1.2
Glass capillaries	1	GD-1.5



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* Please select an adapter that suits the brand of patch amplifier used.

** Any one of the following combinations is possible: AP-12A/L/N x2, AP-13-2 x1, AP-12A/L/N x1 + AP-13-2 x2

Compatibility of patch amplifier adapters

		Manipulator/Patch amplifier adapter				
Headstage make	r and model name	MHW-3 MM-80 NMN-21 MWS-1B MHW		MHW-4		
AXON	HS-2, HS-4, VG-2, VG-2A, CV-4, CV-5, CV-202 (CV-201AU)	AP-12A	AP-14A			
AXUN	CV-203BU, CV-7A/B, HS-9A	AP-13-2	AP-13-3			
НЕКА	EPC-7, EPC-8, EPC-9	AP-12L	AP-14L			
HLNA	EPC-10	AP-13-2	AP-13-3			
Nihon Kohden	JZ-230J, JZ-240J, JZ-245J	AP-12N	AP-14N			



Patch amplifier adapter

Accessories

Micropipette Puller PC-10

The PC-10 is used to pull the glass capillary vertically, utilizing the gravitational force of its own weight. It has two modes: a single pull, pulling capillary at one stretch, and a double pull in which the setting is changed in mid-process. The versatile vertical pull type is suitable for both injection purposes and patch clamping.



Microforge MF-900

The MF-900 is designed to produce injection and holding pipettes. In addition to the temperature and illumination, the position of the heating element can be adjusted.



Pipette Grinder EG-400

The grinder with minimized irregular movements of the grinding plane and the microscope are combined. Precise grinding while confirming needle contact with grinding plane is facilitated.



Micropipette Puller PN-31

The PN-31 uses a pulling method by which a glass capillary is finedrawn using electromagnetic force, enabling the production of long, sharp microneedles. The pulling tension can be adjusted over a wide range, from weak tension that is required at the beginning of pulling to strong tension that is required to make a long, thin microneedle.



Microforge MF-830

A powerful microscope with 525x total magnification is incorporated to make electrodes with tips less than 2µm for patch clamping.



Glass Capillaries G-100, G-1, GD-1/1.2/1.5

G-100 is a thin-walled glass capillary ideal for ICSI, while G-1 is for general purpose.

The GD series is commonly known as double tubing. These glass capillaries contain an internal glass fiber (approx. 100 μ m). The glass capillaries have been prewashed in an ultrasonic washing machine.



Thermal plate warmer ThermoPlate TP series

A temperature-controllable stage ring with a glass-heating plate ensures more accurate and reliable thermal control of specimens. The temperature can be set at between room temperature +5°C and 50°C in 0.1°C increments. A sterilized sensor allows measurement of the actual temperature of dish contents. Management software and continuous current control provide solutions to a wide range of requirements.

Manufactured by Tokai Hit Co., Ltd.



Simple Head Holder Plate (for Mice) MAG-1

After affixing the chamber frame to the head of a mouse, the MAG-1 allows observations/experiments under the microscope or other experimental instruments. Designed to be compact in size, the MAG-1 can be placed under a two-photon microscope or a stereomicroscope.



MAG-1



* Parts for conventional three-point fixation can be customized.



Configuration with Stereo Microscope SMZ18

Photos courtesy of: Masumi Hirabayashi, Associate professor, National Institute for Physiological Sciences

Specimen1: Injection of rat's ES cell into 8-cell embryo

Specimen2: Microinsemination of rat egg

Micromanipulators and related equipment other than microscopes are manufactured by:

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WARNING

TO ENSURE CORRECT USAGE, READ THE CORRESPONDING MANUALS CAREFULLY BEFORE USING YOUR EQUIPMENT.

N.B. Export of the products* in this brochure is controlled under the Japanese Foreign Exchange and Foreign Trade Law. Appropriate export procedure shall be required in case of export from Japan. *Products: Hardware and its technical information (including software)



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